

Space efficient streaming algorithms for the distance to monotonicity and asymmetric edit distance

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Abstract

Approximating the length of the longest increasing sequence (LIS) of a data stream is a well-studied problem. There are many algorithms that estimate the size of the complement of the LIS, referred to as the *distance to monotonicity*, both in the streaming and property testing setting. Let n denote the size of an input array. Our aim is to develop a one-pass streaming algorithm that accurately approximates the distance to monotonicity, and only uses polylogarithmic storage. For any $\delta > 0$, our algorithm provides a $(1 + \delta)$ -multiplicative approximation for the distance, and uses only $O((\log^2 n)/\delta)$ space. The previous best known approximation using poly-logarithmic space was a multiplicative 2-factor. Our algorithm is simple and natural, being just 3 lines of pseudocode. It is essentially a polylogarithmic space implementation of a classic dynamic program that computes the LIS. This leads to additive δn -approximations with poly-logarithmic space, for any constant δ . Previously, it was not known how to get such bounds for $\delta < 1/2$.

Our technique is more general and is applicable to other problems that are exactly solvable by dynamic programs. For example, we are able to get a streaming algorithm for the longest common subsequence problem (in the asymmetric setting introduced in [AKO10]) whose space is small on instances where no symbol appears very many times. Consider two strings (of length n) x and y . The string y is known to us, and we only have streaming access to x . The size of the complement of the LCS is the edit distance between x and y with only insertions and deletions. If no symbol occurs more than k times in y , we get a $O(k(\log^2 n)/\delta)$ -space streaming algorithm that provides a $(1 + \delta)$ -multiplicative approximation for the LCS complement. In general, we also provide a deterministic 1-pass streaming algorithm that outputs a $(1 + \delta)$ -multiplicative approximation for the LCS complement and uses $O(\sqrt{(n \log n)/\delta})$ space. All these algorithms are based on small space streaming algorithms that follow a dynamic program.

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1 Introduction

Finding the longest increasing subsequence (LIS) and longest common subsequence (LCS) of arrays is a classic algorithmic problem. Consider a string x over the alphabet Σ , where x is represented as a function $x : [n] \rightarrow \Sigma$. A subsequence is the string $x(i_1)x(i_2)\dots x(i_k)$, where $1 \leq i_1 < i_2 < \dots < i_k \leq n$. If the alphabet Σ comes equipped with a (total or partial) order \triangleleft , we say that the subsequence is *increasing* if for all j , $x(i_j) \triangleleft x(i_{j+1})$. Given strings x and y , a common subsequence is a string that is a subsequence of both strings. The standard optimization problem of LIS and LCS is to find the appropriate longest subsequence. Note that the LIS of x is the LCS of x and its sorted version.

These problems have standard dynamic programming solutions. The LIS can be found on $O(n \log n)$ time [Sch61, Fre75, AD99]. This is known to be optimal, even for algorithms that only determine the *length* of the LIS [Ram97]. The LCS problem has a fairly direct $O(n^2)$ algorithm [CLRS00], which can be improved to $O(n^2 / \log^2 n)$ [MP80, BFC08]. It is a notoriously difficult open problem to improve this bound, or prove some matching lower bounds.

It is often natural to focus on the complements of the LIS and LCS lengths, which are related to some notion of distances between strings. The size of complement of the LIS is called (edit) *distance to monotonicity*, the minimum number of values that need to be changed to make x monotonically increasing (conventionally, this is represented as fraction of n). The size of the complement of the LCS is the edit distance between x and y , when insertions and deletions are allowed. The standard notion of Levenshtein distance, where insertions, deletions, and substitutions are allowed, is at least half of this edit distance. Naturally, computing these complements exactly is the same as LIS or LCS computations, but approximating these quantities can be very different.

In recent years, there has been a lot of attention on giving approximate solutions for LIS and LCS that are much more efficient than the basic dynamic programming solutions. Any improved results for LCS would be very interesting, since the best known quadratic time solution is infeasible in practice. These problems can be studied in a variety of settings - sampling, streaming, and communication. The streaming setting has been the focus of many results [GJKK07, SW07, GG07, EJ08]. The model for the LIS is that we are allowed one (or constant) passes over the input string x , and only have access to sublinear storage.

For LCS, the streaming model assumes that we stream through both the strings x and y . A recent breakthrough result on approximating edit distance [AKO10] considers an *asymmetric* sampling model. Here, we have full access to the string y and are not charged for reading characters of y . Any access to the string x is accounted for in the query complexity. This is a very helpful model in understanding Levenshtein distance, and a step towards designing better algorithms for LCS. Inspired by this, we consider the *asymmetric streaming model*. We have full access to the string y and the string x is streamed through.

1.1 Results

Our first result is a streaming algorithm for accurately approximating the edit distance to monotonicity. Previous results that either gave only a 2-approximation in poly-logarithmic space [EJ08], or used $\Omega(\sqrt{n})$ space [GJKK07]. (We note that the result of [GJKK07] gave much stronger multiplicative approximations to the LIS in $\Omega(\sqrt{n})$ space.) The error probability of all our algorithms is $n^{-\Omega(1)}$, unless otherwise specified. This also leads to a streaming algorithm providing an additive δn -approximations to the LIS using poly-logarithmic space (for any constant choice of δ). The previous streaming algorithms could only provide an additive $n/2$ -approximation in the worst case. Indeed, when the LIS length was less than $n/2$, previous algorithms would simply return zero as their LIS estimate. Hence, we stress that our improvement from a factor 2 to $(1 + \delta)$ is not just

“chipping away” at a constant, but a fundamental improvement.

Theorem 1.1 *Consider the streaming setting where the input length is n . For any $\delta > 0$, there is a randomized one-pass $O(\delta^{-1} \log^2 n)$ -space streaming algorithm that outputs a $(1 + \delta)$ -multiplicative approximation for the distance to monotonicity of the input stream.*

We observe that this yields an additive δn approximation to the LIS length. This is much stronger than all previous results, which give in the worst case an additive $n/2$ approximation. Our result is actually a corollary of a more general algorithm that finds increasing sequences in partial orders. The main theorem is quite powerful and can also be applied to the asymmetric LCS problem. Given two strings x and y of length n , let $d(x, y)$ be the edit distance under insertions and deletions.

Theorem 1.2 *Consider the asymmetric streaming setting where the input length is n and each symbol occurs at most k times in the string in hand. For any $\delta > 0$, there is a randomized one-pass $O(\delta^{-1} k \log^2 n)$ -space streaming algorithm that outputs a $(1 + \delta)$ -multiplicative approximation to $d(x, y)$. There is also a deterministic one-pass $O(\sqrt{(n \log n)/\delta})$ -space streaming algorithm that outputs a $(1 + \delta)$ -multiplicative approximation to $d(x, y)$, regardless of k .*

As far as we know, there are no algorithms for streaming LCS in this setting. Note the strength of these bounds. The best sub-quadratic algorithm gives only poly-logarithmic factor approximations for the edit distance [AKO10]. (Our algorithm has a large update time, so our total running time is large.) Note that at this range of approximation, both versions of edit distance (with or without substitutions) are basically equivalent. We are able to get extremely accurate approximations for $d(x, y)$ in this streaming setting. When $k = 1$, this corresponds to a variant of the Ulam distance between permutations (edit distance without substitutions). We also give a $\tilde{O}(\sqrt{n})$ space algorithm that is oblivious to k .

1.2 Techniques

One of the most appealing features of our result is the extreme simplicity of the basic algorithm. For finding the LIS of an array, we can give the pseudocode in just a few lines. We define a probability $\alpha(i, t)$ that is approximately $1/\delta(t - i)$. The exact formula is not complicated, but just a little cumbersome to state here. The algorithm maintains a set of indices R , and for each $i \in R$, we store an *estimate* $r(i)$ (the complement of the length of the LIS ending at i) and the number $x(i)$ of the array. For convenience, we add dummy elements $x(0) = x(n + 1) = -\infty$ and begin with $R = \{0\}$. For each time $t \geq 1$, we perform the following update:

1. Define $R' = \{i \in R \mid x(i) \leq x(t)\}$. Set $r(t) = \min_{i \in R'} (r(i) + t - 1 - i)$.
2. $R \leftarrow R \cup \{t\}$.
3. Remove each $i \in R$ independently with probability $\alpha(i, t)$.

The final output is $r(n + 1)/n$, and is guaranteed to be a one-sided $(1 + \delta)$ -approximation to the distance to monotonicity of x . The algorithm is not entirely intuitive, but is incredibly simple in terms of computation. The total amount of space is the maximum size of R , which we can bound above by $O(\delta^{-1} \log^2 n)$ with high probability.

All past poly-logarithmic space algorithms [GJKK07, EJ08] for LIS use combinatorial characterizations of increasing sequences based on inversion counting [EKK⁺00, DGL⁺99, PRR06, ACCL07]. While this is a very powerful technique, it does not lead to accurate approximations for the LIS. Hence, these do not yield any generalizations to LCS, a much harder problem than LIS.

To get around this, we try to follow an exact dynamic program for the LIS. It is known that there are 1-pass streaming algorithms that exactly compute the LIS (using linear space, of course)

[Fre75, AD99]. There has been a $\tilde{O}(\sqrt{n})$ -space deterministic implementation of this, which yields sharp approximations for the LIS length [GJKK07]. We essentially give a *poly-logarithmic* space randomized implementation of this algorithm and prove that it can output sharp approximations for the distance to monotonicity. The algorithm can be generalized to finding long chains in partially ordered streams. Furthermore, as shown earlier, this leads to much simpler streaming algorithms than previous results.

The streaming implementation of the exact dynamic program remembers the length of the LIS up to every index up to the current position, which is a linear amount of information. We save this information only for a set of positions whose density decays exponentially as one moves backwards in time. Notice that since we are not remembering all of the information needed to run the dynamic program, the values we store may not match the corresponding values in the exact dynamic program. The main point is to show that the remembered values are unlikely to drift far away from the values they are intended to approximate.

This idea of remembering selected information about the sequence that becomes sparser as one goes back in time was first used by [GJKK07] for the inversion counting approach. Our work seems to be the first use this to directly mimic the dynamic program. Superficially, it may appear that there is a connection to the sampling based algorithm that obtains a $(1 + \delta)$ -approximation to the distance to monotonicity [SS10]. That result also overcame the 2-factor barrier for sublinear algorithms. We stress that there is little connection between this new streaming algorithm and the sampling based one. This can be clearly seen by just looking at the algorithm - the sampling algorithm was an extremely complex procedure, completely different from the simple 3 lines presented here.

This line of thinking can be exploited to deal with asymmetric streaming LCS. We construct a simple reduction of LCS to finding the longest chain in a specific partial order. This reduction has a streaming implementation, so the input stream can be directly seen as just elements of this resulting partial order. This reduction blows up the size of the input, and the size of the largest chain can become extremely small. If each symbol occurs k times in x and y , then the resulting partial order has nk elements. Nonetheless, the longest chain still has length at most n . We require very accurate estimates for the length of the longest chain. This is where the power of the $(1 + \delta)$ -approximation comes in. We can choose δ to be much smaller to account for the input blow up, and still get a good approximation. Note that if we only had a 1.01-approximation for the longest chain problem, this reduction would not be useful.

Our $\tilde{O}(\sqrt{n})$ -space algorithm also works according to the basic principle of following a dynamic program, although it uses one different from the previous algorithms. This can be thought of as generalization of the $\tilde{O}(\sqrt{n})$ -space algorithm for LIS [GJKK07]. We can basically maintain a $\tilde{O}(\sqrt{n})$ -space deterministic sketch of the data structure maintained by the exact algorithm. By breaking the stream up into the right number of chunks, we can update this sketch using $\tilde{O}(\sqrt{n})$ -space.

1.3 Previous work

The study of LIS and LCS in the streaming setting was initiated by Liben-Nowell et al [LNVZ05], although their focus was mostly on exactly computing the LIS. Sun and Woodruff [SW07] improve upon their algorithms and lower bounds and also prove bounds for the approximate version. Most relevant for our work, they prove that randomized protocols that compute a $(1 + \varepsilon)$ -approximation of the *LIS length* essentially require $\Omega(\varepsilon^{-1} \log n)$. Gopalan et al [GJKK07] provide the first poly-logarithmic space algorithm that approximates the distance to monotonicity. This was based on inversion counting ideas in [PRR06, ACCL07]. Ergun and Jowhari [EJ08] give a 2-approximation using the basic technique of inversion counting, but develop a different algorithm. Gál and Gopalan [GG07] and independently Ergun and Jowhari [EJ08] proved an $\Omega(\sqrt{n})$ lower bound for deterministic protocols that approximate that LIS length upto a multiplicative constant factor. For randomized

protocols, the Sun and Woodruff bound of $\Omega(\log n)$ is the best known. One of the major open problems is to get a $o(\sqrt{n})$ space randomized protocol (or an $\Omega(\sqrt{n})$ lower bound) for constant factor approximations for the LIS length. Note that our work does not imply anything non-trivial for this problem.

A significant amount of work has been done in studying the LIS (or rather, the distance to monotonicity) in the context of property testing [EKK⁺00, DGL⁺99, Fis01, PRR06, ACCL07]. The property of monotonicity has been studied over a variety of domains, of which the boolean hypercube and the set $[n]$ (which is the LIS setting) have usually been of special interest [GGL⁺00, DGL⁺99, FLN⁺02, HK03, ACCL07, PRR06, BGJ⁺09]. In previous work, the authors of this paper found a $(1 + \delta)$ -multiplicative approximation algorithm for the distance that runs in time $O(\text{poly log}(n))$ [SS10]. In that setting, the algorithm has random access to the input but only has time to look at a small fraction of the input (the standard property testing setting). Note the difference from the streaming setting. The streaming algorithm in this paper is completely different from (and much simpler than) the additive approximation algorithm.

The LCS and edit distance have an extremely long and rich history, especially in the applied domain. We point the interesting reader out to [Gus97, Nav01] for more details. Andoni et al [AKO10] achieved a breakthrough by giving a near-linear time algorithm that gives poly-logarithmic time approximations for the edit distance. This followed a long line of results, which is well documented in [AKO10]. Most interestingly, they initiated the study of the *asymmetric edit distance*, where one string is known and we are only charged for accesses to the other string. For the case of non-repetitive strings, there has been a body of work on studying the Ulam distance between permutations [AK07, AK08, AIK09, AN10].

2 Paths in posets

We begin by defining a streaming problem called the *Approximate Minimum-defect path* problem (AMDP). We define it formally below, but intuitively, we look at the stream as a sequence of elements from some poset. Our aim is to estimate the size of the complement of the longest chain, consistent with the stream ordering. This is more general problem than LIS, and we will later show how streaming algorithms for LIS and LCS can be obtained from reductions to AMDP.

2.1 Weighted P -sequences and the approximate minimum-defect path problem

We use P to denote a fixed set endowed with a partial order \triangleleft . The partial order relation is given by an oracle which, given $u, v \in P$ outputs $u \triangleleft v$ or $\neg(u \triangleleft v)$. For a natural number n we write $[n]$ for the set $\{1, 2, \dots, n\}$.

A sequence $\sigma = (\sigma(1), \dots, \sigma(n)) \in P$ is called a P -sequence. The number of terms σ is called the length of σ and is denoted $|\sigma|$; we normally use n to denote $|\sigma|$. A *weighted P -sequence* consists of a P -sequence σ together with a sequence $(w(1), \dots, w(n))$ of nonnegative integers; $w(i)$ is called the *weight* of index i . In all our final applications $w(i)$ will always be 1. Nonetheless, we solve this slightly more general weighted version.

We have the following additional definitions:

- For $t \in [n]$, $\sigma_{\leq t}$ denotes the sequence $(\sigma_1, \dots, \sigma_t)$. Also for $J \subseteq [n]$, $J_{\leq t}$ denotes the set $J \cap \{1, \dots, t\}$.
- For $J \subseteq [n]$, $w(J) = \sum_{j \in J} w(j)$.
- The digraph $D = D(\sigma)$ associated to the P -sequence σ has vertex set $[n]$ (where $n = |\sigma|$) and arc set $\{i \rightarrow j : i < j \text{ and } \sigma(i) \triangleleft \sigma(j)\}$.

- A path π in $D(\sigma)$ is called a σ -path. Such a path is a sequence $1 \leq \pi_1 < \dots < \pi_k \leq n$ of indices with $\pi_1 \longrightarrow \dots \longrightarrow \pi_k$. We say that π ends at π_k .
- The *defect of path* π , $\text{defect}(\pi)$ is defined to be $w([n] - \pi)$.
- $\text{min-defect}(\sigma, w)$ is defined to be the minimum of $\text{defect}(\pi)$ over all σ -paths π .

We now define the *Approximate Minimum-defect path* problem (AMDP). The input is a weighted P -sequence (σ, w) , an approximation parameter $\delta > 0$, and an error parameter $\gamma > 0$. The output is a number A such that: $\text{Prob}[A \in [\text{min-defect}(\sigma, w), (1 + \delta)\text{min-defect}(\sigma, w)]] \geq 1 - \gamma$. An algorithm for AMDP that has the further guarantee that $A \geq \text{min-defect}(\sigma, w)$ is said to be a *one-sided error algorithm*.

2.2 Streaming algorithms and the main result

In a one-pass streaming algorithm, the algorithm has one-way access to the input. For the AMDP, the input consists of the parameters δ and γ together with a sequence of n pairs $((\sigma(t), w(t)) : t \in [n])$. We think of the input as arriving in a sequence of discrete time steps, where δ, γ arrive at time step 0 and for $t \in [n]$, $(\sigma(t), w(t))$ arrives at time step t .

The main complexity parameter of interest is the auxiliary memory needed. For simplicity, we assume that each memory cell can store any one of the following: a single element of P , an index in $[n]$, or an arbitrary sum $w(J)$ of distinct weights. Associated to a weighted P -sequence (σ, w) we define the parameter: $\rho = \rho(w) = \sum_i w_i$. Typically one should think of the weights as bounded by a polynomial in n and so $\rho = n^{O(1)}$. The main technical theorem about AMDP is the following.

Theorem 2.1 *There is a randomized one-pass streaming algorithm for AMDP that operates with one-sided error and uses space $O(\frac{\ln(n/\gamma) \ln(\rho)}{\delta})$.*

In particular, if $\rho = n^{O(1)}$ and $\gamma = 1/n^{O(1)}$ then the space is $O(\frac{(\ln(n))^2}{\delta})$.

3 The algorithm

Our streaming algorithm can be viewed as a modification of a standard dynamic programming algorithm for exact computation of $\text{min-defect}(\sigma, w)$. We first review this dynamic program.

3.1 Exact computation of $\text{min-defect}(\sigma, w)$

It will be convenient to extend the P -sequence by an element $\sigma(n+1)$ that is greater than all other elements of P . Thus all arcs $j \longrightarrow n+1$ for $j \in [n]$ are present. Set $w(n+1) = 0$. We define sequences $s(0), \dots, s(n+1)$ and $W(0), \dots, W(n+1)$ as follows. We initialize $s(0) = 0$ and $W(0) = 0$. For $t \in [n+1]$:

$$\begin{aligned} W(t) &= W(t-1) + w(t) \\ s(t) &= \min(s(i) + W(t-1) - W(i) : i < t \text{ such that } \sigma_i \longrightarrow \sigma_t). \end{aligned}$$

Thus $W(t) = w([t])$. It is easy to prove by induction that $s(t)$ is equal to the minimum of $W(t) - w(\pi)$ over all paths π whose maximum element is $\sigma(t)$. In particular, $\text{min-defect}(\sigma, w) = s(n+1)$.

The above recurrence can be implemented by a one-pass streaming algorithm that uses linear space (to store the values of $s(t)$ and $W(t)$).

3.2 The poly-log space streaming algorithm

We denote our streaming algorithm by $\Gamma = \Gamma(\sigma, w, \delta, \gamma)$. Our approximation algorithm is a natural variant of the exact algorithm. At step t the algorithm computes an approximation $r(t)$ to $s(t)$. The difference is that rather than storing $r(i)$ and $W(i)$ for all i , we store them only for an evolving subset R of indices, called the *active set* of indices. The amount of space used by the algorithm is proportional to the maximum size of R .

We first define the probabilities $p(i, t)$. Similar quantities were defined in [GJKK07].

$$q(i, t) = \min \left\{ 1, \frac{1 + \delta}{\delta} \ln(4t^3/\gamma) \frac{w(i)}{W(t) - W(i-1)} \right\}$$

$$p(i, i) = 1 \quad p(i, t) = \frac{q(i, t)}{q(i, t-1)} \text{ for } t > i,$$

We initialize $R = \{0\}$, $r(0) = 0$ and $W(0) = 0$. The following update is performed for each time step $t \in [n+1]$. The final output is just $r(n+1)$.

1. $W(t) = W(t-1) + w(t)$.
2. $r(t) = \min(r(i) + W(t-1) - W(i) : i \in R \text{ such that } \sigma_i \rightarrow \sigma_t)$.
3. The index t is inserted in R . Each element $i \in R$ is (independently) discarded with probability $1 - p(i, t)$.

We will prove:

Theorem 3.1 *On input $(\sigma, w, \delta, \gamma)$, the algorithm Γ satisfies:*

- $r(n+1) \geq \text{min-defect}(\sigma, w)$.
- $\text{Prob}[r(n+1) > (1 + \delta)\text{min-defect}(\sigma, w)] \leq \gamma/2$.
- *The probability that $|R|$ ever exceeds $\frac{2e^2}{\delta} \ln(2\rho) \ln(4n^3/\gamma)$ is at most $\gamma/2$.*

The above theorem does not exactly give what was promised in Theorem 2.1. For the algorithm Γ , there is a small probability that the set R exceeds the desired space bound while Theorem 2.1 promises an upper bound on the space used. To achieve the guarantee of Theorem 2.1 we modify Γ to an algorithm Γ' which checks whether R ever exceeds the desired space bound, and if so, switches to a trivial algorithm which only computes the sum of all weights and outputs that. This guarantees that we stay within the space bound, and since the probability of switching to the trivial algorithm is at most $\gamma/2$, the probability that the output of Γ' exceeds $(1 + \delta)\text{min-defect}(\sigma, w)$ is at most γ .

We now prove Theorem 3.1. The first assertion is a direct consequence of the following proposition.

Proposition 3.1 *For all $j \leq n+1$ we have $r(j) \geq s(j)$ and thus $r(n+1) \geq \text{min-defect}(\sigma, w)$.*

The second part will be proved in the two subsection. The final assertion of Theorem 3.1 showing the space bound is deferred to Appendix A.

3.3 Quality of estimate bound of Theorem 3.1

We prove the second assertion of Theorem 3.1, which is the main technical part of the proof. Let R_t denote the set R after processing $\sigma(t), w(t)$. Observe that the definition of $p(i, j)$ implies:

Proposition 3.2 *For each $i \leq t \leq n$, $\text{Prob}[i \in R_t] = \prod_{j \in [i, t]} p(i, j) = q(i, t)$.*

We need some additional definitions.

- For $I \subseteq [n + 1]$, we denote $[n + 1] - I$ by \bar{I} .
- Let C be the index set of some fixed chain having minimum defect. We assume without loss of generality that $n + 1 \in C$.
- We write R^t for the subset R at the end of step t . Note that $R^t \subseteq [t]$. We define $F^t = [t] - R^t$. An index $i \in R^t$ is said to be *remembered at time t* and $i \in F^t$ is said to be *forgotten by time t* .
- Index $i \in C$ is said to be *unsafe at time t* if every index in $C \cap [i, t] \subseteq F^t$, i.e., every index of $C \cap [i, t]$ is forgotten by time t . We write U^t for the set of indices that are unsafe at time t .
- An index $i \in C$ is said to be *unsafe* if it is unsafe for some time $t > i$ and is *safe* otherwise. We denote the set of unsafe indices by U . On any execution, the set U is determined by the sequence R^1, \dots, R^n .

Lemma 3.3 *On any execution of the algorithm, $r(n + 1) \leq w(\bar{C} \cup U)$.*

Proof: We prove by induction on t that if $t \in C$ then $r(t) \leq w(\bar{C}_{\leq t-1} \cup U^{t-1})$. Assume $t \geq 1$ and that the result holds for $j < t$. We consider two cases.

Case i. $U^{t-1} = C_{\leq t-1}$. Then $w(\bar{C}_{\leq t-1} \cup U^{t-1}) = W(t - 1)$. By definition $r(t) \leq r(0) + W(t - 1) - W(0) = W(t - 1)$, as required.

Case ii. $U^{t-1} \neq C_{\leq t-1}$. Let j be the maximum index in $C_{\leq t-1} - U^{t-1}$. Since $j, t \in C$ we must have $\sigma(j) \rightarrow \sigma(t)$. Therefore by the definition of $r(t)$ we have: $r(t) \leq r(j) + W(t - 1) - W(j)$. By the induction hypothesis we have $r(j) \leq w(\bar{C}_{\leq j-1} \cup U^{j-1})$. Since j is the largest element of $C_{\leq t-1} - U^{t-1}$ we have: $\bar{C}_{\leq t-1} \cup U^{t-1} = \bar{C}_{\leq j-1} \cup U^{j-1} \cup [j + 1, t - 1]$, and so:

$$r(t) \leq r(j) + W(t - 1) - W(j) \leq w(\bar{C}_{\leq j-1} \cup U^{j-1} \cup [j + 1, t - 1]) \leq w(\bar{C}_{\leq t-1} \cup U^{t-1})$$

□

By Lemma 3.3 the output of the algorithm is at most $w(\bar{C}) + w(U) = \text{min-defect}(\sigma, w) + w(U)$. It now suffices to prove:

$$\text{Prob}[w(U) \geq \delta w(\bar{C})] \leq \gamma/2. \quad (1)$$

Call an interval $[i, j]$ *dangerous* if $w(C \cap [i, j]) \leq w([i, j])(\delta/(1 + \delta))$. In particular $[i, i]$ is dangerous iff $i \notin C$. Call an index i dangerous if it is the left endpoint of some dangerous interval. Let D be the set of all dangerous indices.

We define a sequence I_1, I_2, \dots, I_ℓ of disjoint dangerous intervals as follows. If there is no dangerous interval then the sequence is empty. Otherwise:

- Let i_1 be the smallest index in D and let I_1 be the largest interval with left endpoint i_1 .
- Having chosen I_1, \dots, I_j , if D contains no index to the right of all of the chosen intervals then stop. Otherwise, let i_{j+1} be the least index in D to the right of all chosen intervals and let I_{j+1} be the largest dangerous interval with left endpoint i_{j+1} .

It is obvious from the definition that each successive interval lies entirely to the right of the previously chosen intervals. Let $B = I_1 \cup \dots \cup I_\ell$ and let $\bar{B} = [n] - B$. We now make a series of observations:

Claim 3.4 $\bar{C} \subseteq D \subseteq B$.

Claim 3.5 $w(B) \leq w(\bar{C})(1 + \delta)$.

Claim 3.6 $\text{Prob}[U \subseteq B] \geq 1 - \gamma/2$.

By Claims 3.4 and 3.6, we have $U \cup \bar{C} \subseteq B$ with probability at least $1 - \gamma/2$, and so by Claim 3.5, $w(U \cup \bar{C}) \leq w(\bar{C})(1 + \delta)$ with probability at least $1 - \gamma/2$, establishing (1).

Thus it remains to prove the claims.

Proof of Claim 3.4: If $i \in \bar{C}$ then, as noted earlier, i is dangerous so $i \in D$.

Now suppose $i \in D$. By the construction of the sequence of intervals, there is at least one interval I_1 and the left endpoint i_1 is at most i . If $i \in I_1 \subseteq B$, we're done. So assume $i \notin I_1$ and so i is to the right of I_1 . Let j be the largest index for which i is to the right of I_j . Then I_{j+1} exists and $i_{j+1} \leq i$. Since I_{j+1} is not entirely to the right of i we must have $i \in I_{j+1} \subseteq B$.

Proof of Claim 3.5: For each I_j we have $w(I_j \cap C) \leq w(I_j)\delta/(1 + \delta)$. Therefore $w(I_j \cap \bar{C}) \geq w(I_j)/(1 + \delta)$ and so $(1 + \delta)w(I_j \cap \bar{C}) \geq w(I_j)$. Summing over I_j we get $(1 + \delta)w(\bar{C}) \geq w(B)$.

Proof of Claim 3.6: We fix $t \in [n]$ and $i \in \bar{B} \cap [t]$ and show $\text{Prob}[i \in U^t] \leq \frac{\gamma}{4t^3}$. This is enough to prove the claim since we will then have:

$$\begin{aligned} \text{Prob}[U \subseteq B] = 1 - \text{Prob}[\bar{B} \cap U \neq \emptyset] &\geq 1 - \sum_{t=1}^n \text{Prob}[\bar{B} \cap U^t \neq \emptyset] \\ &\geq 1 - \sum_{t=1}^n \sum_{i \in \bar{B} \cap [t]} \text{Prob}[i \in U^t] \geq 1 - \sum_{t=1}^n \sum_{i \in \bar{B} \cap [t]} \frac{\gamma}{4t^3} \geq 1 - \gamma/2. \end{aligned}$$

So fix t and $i \in \bar{B} \cap [t]$. Since $i \notin B$, the interval $[i, t]$ is not dangerous, and so $w(C \cap [i, t]) \geq w([i, t])\delta/(1 + \delta)$, and so

$$w([i, t]) \leq \frac{1 + \delta}{\delta} w(C \cap [i, t]). \quad (2)$$

We have $i \in U^t$ only if every index of $C \cap [i, t]$ is forgotten by time t . For $j \leq t$, the probability that index $j \in t$ has been forgotten by time t is $1 - q(j, t)$ so $\text{Prob}[i \in U^t] = \prod_{j \in C \cap [i, t]} (1 - q(j, t))$. If $q(j, t) = 1$ for any of the multiplicands then the product is 0. Otherwise for each $j \in C \cap [i, t]$:

$$q(j, t) = \frac{1 + \delta}{\delta} \ln(4t^3/\gamma) \frac{w(j)}{(W(t) - W(j - 1))} \geq \ln(4t^3/\gamma) \frac{1 + \delta}{\delta} \frac{w(j)}{w([i, t])} \geq \ln(4t^3/\gamma) \frac{w(j)}{w(C \cap [i, t])},$$

where the final inequality uses (2). Therefore:

$$\text{Prob}[i \in U(t)] \leq \prod_{j \in C \cap [i, t]} (1 - q(j, t)) \leq \exp\left(- \sum_{j \in C \cap [i, t]} q(j, t)\right) \leq \gamma/4t^3,$$

as required to complete the proof of Claim 3.6, and of the second assertion of Theorem 3.1.

4 Applying AMDP to LIS and LCS

We now show how to apply Theorem 2.1 to LIS and LCS. The application to LIS is quite obvious. We first set some notation about points in the two-dimensional plane. We will label the axes as 1 and 2, and for a point z , $z(1)$ (resp. $z(2)$) refers to the first (resp. second) coordinate of z . We use the standard coordinate-wise partial order on z . So $z \triangleleft z'$ iff $z(1) < z'(1)$ and $z(2) < z'(2)$.

Proof: (of Theorem 1.1) The input is a stream $(x(1), x(2), \dots, x(n))$. Think of the i th element of the stream as the point $(i, x(i))$. So the input is thought of as a sequence of points. Note that the points arrive in increasing order of first coordinate. Hence, a chain in this poset corresponds exactly to an increasing sequence (and vice versa). We set $\gamma = n^{O(1)}$ and $\rho = n$ in Theorem 2.1. \square

The application to LCS is somewhat more subtle. Again, we think of the input as a set of points in the two-dimensional plane. But this transformation will lead to a blow up in size, which we counteract by choosing a small value of δ .

Theorem 4.1 *Let x and y be two strings of length where each character occurs at most k times in y . Then there is a $O(\delta^{-1}k \log^2 n)$ -space algorithm for the asymmetric setting that outputs a multiplicative $(1 + \delta)$ -approximation of $d(x, y)$.*

Proof: We show how to convert an instance of approximating $d(x, y)$ in the asymmetric model to an instance of AMDP. Let P be the set of pairs $\{(i, j) | x(i) = y(j)\}$ under the product order $(i, j) \leq (i', j')$ if $i \leq i'$ and $j \leq j'$. It is easy to see that common subsequences of x and y correspond to chains in this poset.

Now we associate to the pair of strings x, y the sequence σ consisting of points in P listed lexicographically ((i, j) precedes (i', j') if $i < i'$ or if $i = i'$ and $j < j'$.) Note that σ can be constructed online given streaming access to x : when $x(i)$ arrives we generate all pairs with first coordinate i in order by second coordinate. Again it is easy to check that common subsequences of x and y correspond to σ -paths as defined in the AMDP. Thus the length of the LIS is equal to the size of the largest σ -path. It is not true that $d(x, y)$ is equal to $\min - defect(\sigma)$ (here we omit the weight function, which we take to be identically 1), because the length of σ is, in general longer than n . Given full access to y , and a streamed x . We have a bound on $|\sigma|$ of nk since each symbol appears at most k times in x .

We now argue that a $(1 + \delta)$ -approximation for $d(x, y)$ can be obtained from a $(1 + \delta/k)$ -approximation for AMDP of P . Let the length of the longest chain in P be ℓ and the min-defect be m . Let d be a shorthand for $d(x, y)$. We have $\ell + m = |P|$ and $\ell + d = n$. The output of AMDP is an estimate est such that $m \leq est \leq (1 + \delta/k)m$. We estimate d by $est_d = est + n - |P|$. We show that $est_d \in [d, (1 + \delta)d]$.

We have $est_d = est + n - |P| \geq m + n - |P| = n - \ell = d$. We can also get an upper bound.

$$est_d = est + n - |P| \leq m + n - |P| + \delta m/k = d + \delta(|P| - \ell)/k \leq d + \delta(n - \ell) = (1 + \delta)d$$

Hence, we use the parameters $\delta/k, \gamma = n^{O(1)}$ for the AMDP instance created by our reduction. An application of Theorem 2.1 completes the proof. \square

5 Deterministic streaming algorithm for LCS

We now discuss a deterministic \sqrt{n} -space algorithm for LCS. This can be used for small sized alphabets to beat the bound given in Theorem 4.1. For any consistent sequence (CS), the size of the complement is called the *defect*. For indices $i, j \in [n]$, $x(i, j)$ refers to the substring of x from the i th character upto the j th character. The main theorem is:

Theorem 5.1 *Let $\delta > 0$. We have strings x and y with full access to y and streaming access to x . There is a deterministic one-pass streaming algorithm that computes a $(1 + \delta)$ -approximation to $d(x, y)$ that uses $O(\sqrt{(n \ln n)/\delta})$ space. The algorithm performs $O(\sqrt{(\delta n)/\ln n})$ updates, each taking $O(n^2 \ln n/\delta)$ time.*

The following claim is a direct consequence of the standard dynamic programming algorithm for LCS [CLRS00].

Claim 5.2 *Suppose we are given two strings x and y , with complete access to y and a one-pass stream through x . There is an $O(n)$ -space algorithm that guarantees the following: when we have seen $x(1, i)$, we have the lengths of the LCS between $x(1, i)$ and $y(1, j)$, for all $j \in [n]$.*

Our aim is to implement this algorithm in sublinear space. As before, we maintain a carefully chosen snapshot of the $O(n)$ -space used by the algorithm. In some sense, we only maintain a small subset of the partial solutions. Although we do not explicitly present it in this fashion, it may be useful to think of the reduction of Theorem 4.1. We convert an LCS into finding the longest chain in a set of points P . We construct a set of *anchor points* in the plane, which may not be in P . Our aim is to just maintain the longest chain between pairs of anchor points.

Let $\delta > 0$ be some fixed parameter. We set $\bar{n} = \sqrt{(n \ln n)/\delta}$ and $\mu = (\ln n)/\bar{n} = \sqrt{(\delta \ln n)/n}$. For each $i \in [n/\bar{n}]$, the set S_i of indices is defined as follows.

$$S_i = \{ \lfloor i\bar{n} + b(1 + \mu)^r \rfloor \mid r \geq 0, b \in \{-1, +1\} \}$$

For convenience, we treat \bar{n} , n/\bar{n} , and $(1 + \mu)^r$ as integers¹. So we can drop the floors used in the definition of S_i . Note that the $|S_i| = O(\mu^{-1} \ln n) = O(\bar{n})$. We refer to the family of sets $\{S_1, S_2, \dots\}$ by \mathcal{S} . This is the set of anchor points that we discussed earlier. Note that they are placed according to a geometric grid.

Definition 5.3 *A common subsequence of x and y is consistent with \mathcal{S} if the following happens. There exists a sequence of indices $\ell_1 \leq \ell_2 \leq \dots \leq \ell_m$ such that $\ell_i \in S_i$ and if character $x(k)$ ($k \in [i\bar{n}, (i+1)\bar{n}]$) in the common subsequence is matched to $y(k')$, then $k' \in [\ell_i, \ell_{i+1}]$.*

We now have a basic claims about the LCS of two strings (proof deferred to Appendix B). This gives us some a simple bound on the defect that we shall exploit. Lemma 5.5 makes an important argument. It argues that the the anchor points \mathcal{S} were chosen such that an \mathcal{S} -consistent sequence is “almost” the LCS.

Claim 5.4 *Consider an $x(i_1), x(i_2), \dots, x(i_r)$ and $y(j_1), y(j_2), \dots, y(j_r)$. Suppose i_a is the smallest index with value at least i . The defect is at least $|j_a - i|$.*

Lemma 5.5 *There exists an \mathcal{S} -consistent common subsequence of x and y whose defect is at most $(1 + \delta)d(x, y)$.*

Proof: We start with an LCS L of x and y and “round” it to be \mathcal{S} -consistent. Let L be $x(i_1), x(i_2), \dots, x(i_r)$ and $y(j_1), y(j_2), \dots, y(j_r)$. Consider some $p \in [n/\bar{n}]$, and let i_a be the smallest index larger than $p\bar{n}$. Set ℓ_p to be the largest index in S_p smaller than j_a . We construct a new common sequence L' by removing certain matches from L . Consider a matched pair $(x(i_b), y(j_b))$ in L . If $i_b \in [p\bar{n}, (p+1)\bar{n}]$ and $j_b \leq \ell_{p+1}$, then we add this pair to L' . Otherwise, it is not added. Note that $j_b \geq \ell_p$, simply by construction. The new common sequence L' is \mathcal{S} -consistent.

¹Formally, we need to take floors of these quantities. Our analysis remains identical.

It now remains to bound the defect of L' . Consider a matched pair $(x(i_b), y(j_b)) \in L$ that is not present in L' . Let $i_b \in [(p-1)\bar{n}, p\bar{n}]$. This means that $j_b > \ell_p$. Let i_c be the smallest index larger than $p\bar{n}$. So ℓ_p is the largest index in S_p smaller than j_c . Let $\ell_p = p\bar{n} + (1 + \mu)^r$. We have $j_c - p\bar{n} = [(1 + \mu)^r, (1 + \mu)^{r+1}]$. Since $j_b \in [\ell_p, j_c]$, the total possible values for j_b is at most $(1 + \mu)^{r+1} - (1 + \mu)^r = \mu(1 + \mu)^r$. By Claim 5.4, $d(x, y) \geq j_c - p\bar{n} \geq (1 + \mu)^r$. The number of characters of x with indices in $[(p-1)\bar{n}, p\bar{n}]$ that are not in L' is at most $\mu d(x, y)$. The total number of characters of L' not in L is at most $\mu(n/\bar{n})d(x, y) \leq \delta d(x, y)$. \square

The final claim shows how we to update the set of partial LCS solutions consistent with the anchor points. The proof of this claim and the final proof of the main theorem (that puts everything together) is given in Appendix B.

Claim 5.6 *Suppose we are given the lengths of the largest \mathcal{S} -consistent common subsequences between $x(1, i\bar{n})$ and $y(1, j)$, for all $j \in S_i$. Also, suppose we have access to $x(i\bar{n}, (i+1)\bar{n})$ and y . Then, we can compute the lengths of the largest \mathcal{S} -consistent common sequences between $x(1, (i+1)\bar{n})$ and $y(1, j)$ (for all $j \in S_{i+1}$) using \bar{n} space. The total running time is $O(n\bar{n}^2)$.*

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A The space bound of Theorem 3.1

The following claim bounds the probability that $|R_t|$ exceeds the space bound is at most $\gamma/2n$. A union bound over all t proves the third assertion of Theorem 3.1.

Claim A.1 *Let $M = \frac{2}{\delta} \ln(4n^3/\gamma) \ln(2\rho)$. Fix $t \in [n]$. Then $\text{Prob}[|R_t| \geq e^2 M] \leq \gamma/2n$.*

Proof: For $i \in [t]$ let $Z_i = 1$ if $i \in R_t$ and 0 otherwise. Then $|R_t| = \sum_{i \leq t} Z_i$. Let $\mu = \mathbb{E}[|R_t|]$. Below we show that $\mu \leq M$. We need the following tail bound (which is equivalent to the bound of [AS00], Theorem A.12):

Proposition A.2 *Let Z_1, \dots, Z_m be independent 0/1-valued random variables, let $Z = \sum_i Z_i$, and let $\mu = \mathbb{E}[Z]$. Then for any $C \geq 0$, $\text{Prob}[Z \geq C] \leq (e\mu/C)^C$.*

Applying this proposition with $C = e^2 M$ gives $\text{Prob}[|R_t| \geq e^2 M] \leq e^{-C}$ which is at most $\gamma/2n$ (with a lot of room to spare). It remains to upper bound μ . Denoting the upper bound by M , we conclude that:

$$\mu = \sum_{i=1}^t \mathbb{E}[Z_i] = \sum_{i=1}^t q(i, t) \leq \frac{2}{\delta} \ln(4n^3/\gamma) \sum_{i=1}^t w(i)/(W(t) - W(i-1)).$$

We note the following fact (easily proved by induction on r):

Proposition A.3 *For $r \geq 1$, $\sum_{i=r}^t w(i)/(W(t) - W(i-1)) \leq \ln(\frac{2(W(t)-W(r-1))}{w(t)})$.*

Thus $\sum_{i=1}^t w(i)/(W(t) - W(i-1)) \leq \ln(2W(t)/w(t)) \leq \ln(2\rho)$, and so $\mu \leq M$. This completes the proof. \square

B Proofs from Section 5

We first prove another claim from which the proof of Claim 5.4 follows.

Claim B.1 *Given a common subsequence $x(i_1), x(i_2), \dots, x(i_r)$ and $y(j_1), y(j_2), \dots, y(j_r)$, the defect is at least $\max_{k \leq r} (|i_k - j_k|)$.*

Proof: (of Claim B.1) Assume wlog that $i_k \geq j_k$. Since the i_k th character of x is matched to j_k th character of y , the length of this common subsequence is at most $LCS(x(1, i_k), y(1, j_k)) + LCS(x(i_k + 1, n), y(j_k + 1, n))$. This can be bounded above trivially by $j_k + (n - i_k) = n - (i_k - j_k)$. Hence the defect is at least $i_k - j_k$. Repeating over all k , we complete the proof. \square

Proof: (of Claim 5.4) The defect is at least $|j_a - i_a|$ (by Claim B.1) and is also at least $|i_a - i|$ (by definition of i_a). If either $j_a \in [i, i_a]$ or $i \in [j_a, i_a]$, then the defect is certainly at least $|j_a - i|$. Suppose neither of these are true. Then $j_a > i_a \geq i$. Let us focus on the characters of x that are not matched. No character of x with index in $[i, i_a]$ is matched. The characters in $(i_a, n]$ can only be matched to characters of y in $(j_a, n]$ (since $(x(i_a), y(j_a))$ is a match). So the number of characters in $(i_a, n]$ that are *not matched* is at least $(n - i_a) - (n - j_a) = (j_a - i_a)$. So the number of unmatched characters in x is at least $j_a - i$. \square

Proof: (of Claim 5.6) Consider some $j \in S_{i+1}$, and set $\bar{x} = x(i\bar{n}, (i+1)\bar{n})$. We wish to compute the largest \mathcal{S} -consistent CS between in $x(1, (i+1)\bar{n})$ and $y(1, j)$. Suppose we look at the portion of this CS in $x(1, i\bar{n})$. This forms a \mathcal{S} -consistent sequence between \bar{x} and $y(1, j')$, for some $j' \in S_i$. The remaining portion of the CS is just the LCS between $\bar{x} = x(i\bar{n}, (i+1)\bar{n})$ and $y(j', j)$. Hence, given the LCS length of \bar{x} and $y(j', j)$, for all $j' \in S_i$, we can compute the length of the largest \mathcal{S} -consistent CS between $x(1, (i+1)\bar{n})$ and $y(1, j)$. This is obtained by just maximizing over all possible j' .

We now apply Claim 5.2. We have \bar{x} in hand, and stream in reverse order through $y(1, j)$. Using $O(\bar{n})$ space, we can compute all the LCS lengths desired. This gives the length of the largest \mathcal{S} -consistent CS that ends at $y(j)$. This can be done for all $y(j)$, $j \in S_i$. The total running time is $O(|S_{i+1}|n\bar{n}) = O(n\bar{n}^2)$. \square

Proof: (of Theorem 5.1) Our streaming algorithm will compute the length of the longest \mathcal{S} -consistent CS. Consider the index $i\bar{n}$. Suppose we have currently stored the lengths of the largest \mathcal{S} -consistent CS between $x(1, i\bar{n})$ and $y(1, j)$, for all $j \in S_i$. This requires space $O(|S_i|) = O(\bar{n})$. By Claim 5.6, we can compute the corresponding lengths for S_{i+1} using an additional $O(\bar{n})$ space. Hence, at the end of the stream, we will have the length (and defect) of the longest \mathcal{S} -consistent CS. Lemma 5.5 tells us that this defect is a $(1 + \delta)$ -approximation to $d(x, y)$. The space bound is $O(\bar{n})$.

The number of updates is $O(n/\bar{n}) = O(\sqrt{(\delta n)/\ln n})$, and the time for each update is $O(n\bar{n}^2) = O((n^2 \ln n)/\delta)$. \square